## RRTRANSFORMER#1: A Long-haul Wireless Mesh Network

## Infrastructure of Unmanned Buoys for Underwater Sensors

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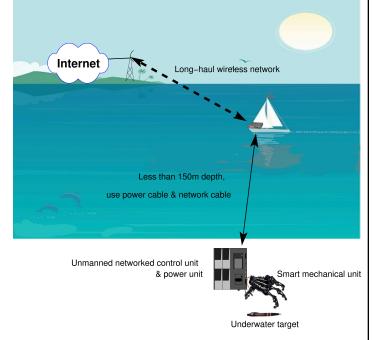
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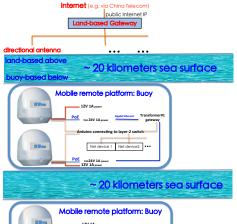
- Unmanned ocean exploration: The State Oceanic Administration (SOA) requests that the unmanned buoys must work autonomously for at least 60 days without human on board
- Localized and precise knowledge acquisition: The presence of a set of automated vehicles, e.g., buoys and unmanned boats, is needed in a underwater event's neighborhood to do localized and precise information collection











**Technical specification** 

- Dimensions (including a directional antenna): 60cm (height) × 90cm (diameter)
- Device operation temperature: −30°C -- 70°C
- Overall rotating weight: 8kg
- Number of rotating axes: single (for water surface or ground surface communication), double (for aerial communication)
- Rotating speed: 20°/second
- Overall power consumption (including mechanical operations, radio transmissions and computer operations): 40 watts (maximum), 20 watts (average)
- Vertical target aiming angle: ±30° maximum, or totally 60°
- Horizontal target aiming angle: unlimited
- Antenna gain: 21 dBi
- Antenna polarization: dual linear
- Frequency range: 5179 -- 5875 MHz
- Transmission power: 27 dBm
  - Communication speed: 10Mbps at 20km range

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